

R88D-GN□, R88D-GT□

# G-Series servo drive

**A compact servo drive family for motion control. Compact size and integrated MECHATROLINK-II motion bus.**

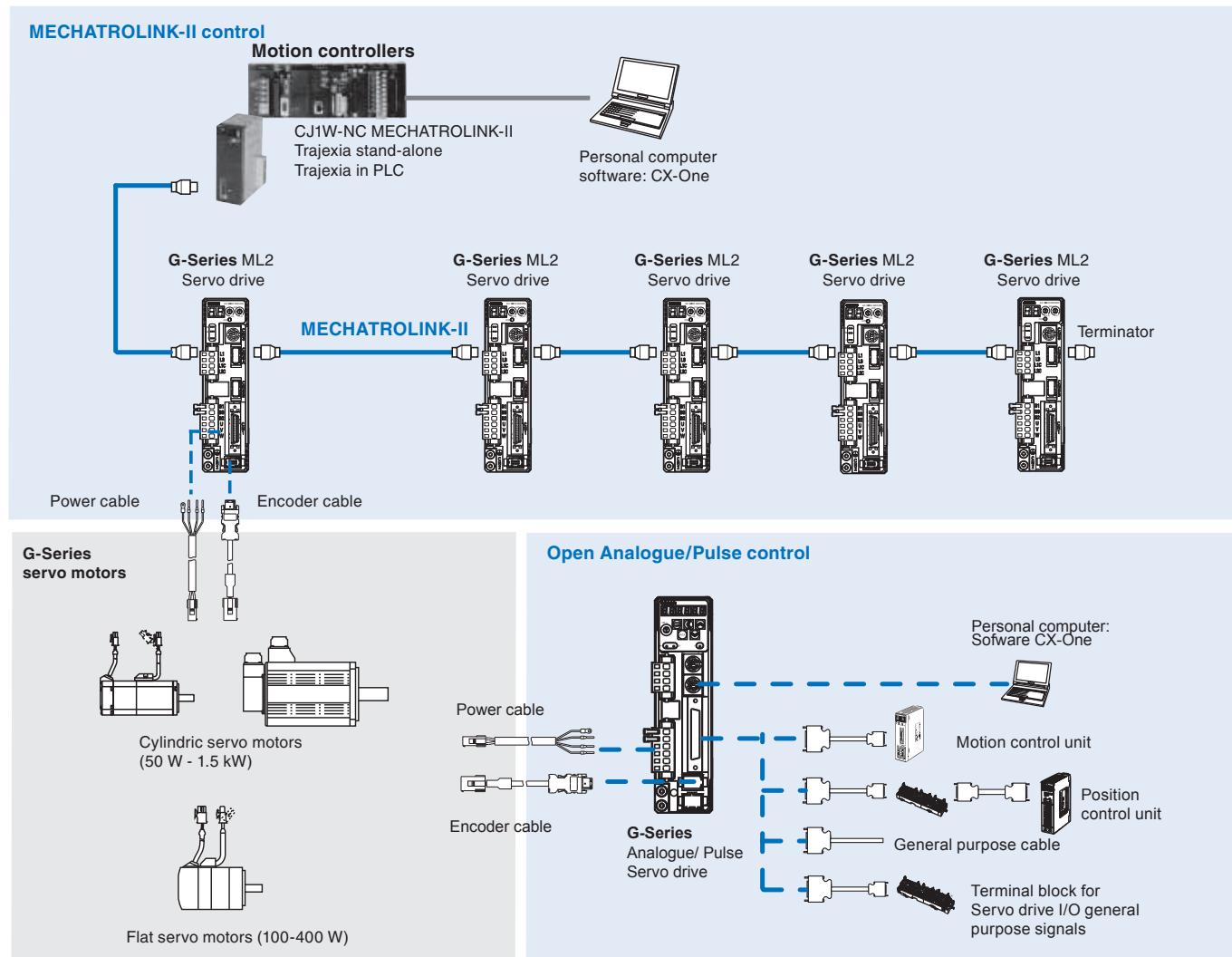
- ML2 and Analog/ Pulse servo drive models
- High-response frequency of 1 kHz
- Auto-tuning for easy and quick start-up
- Vibration suppression
- Positioning, speed or torque control
- Separate power and control power supply
- Fast and accurate positioning
- Incremental and absolute encoder

## Ratings

- 230 VAC Single-phase 100 W to 1.5 kW (8.62 Nm)



## System configuration



## Servo motor supported

Servo motor						G-Series servo drive			
Family	Voltage	Speed	Rated torque	Capacity	Model	MECHATROLINK-II	Analog/ Pulse		
Cylindric	50 - 750 W 	230 V	3000 min <sup>-1</sup>	0.16 Nm	50 W	R88M-G05030□-□S2	R88D-GN01H-ML2		
				0.32 Nm	100 W	R88M-G10030□-□S2	R88D-GN01H-ML2		
				0.64 Nm	200 W	R88M-G20030□-□S2	R88D-GN02H-ML2		
				1.3 Nm	400 W	R88M-G40030□-□S2	R88D-GN04H-ML2		
				2.4 Nm	750 W	R88M-G75030□-□S2	R88D-GN08H-ML2		
	900 - 1500 W 			3.18 Nm	1000 W	R88M-G1K030T-□S2	R88D-GN15H-ML2		
				4.77 Nm	1500 W	R88M-G1K530T-□S2	R88D-GN15H-ML2		
	2000 min <sup>-1</sup>		4.8 Nm	1000 W	R88M-G1K020T-□S2	R88D-GN10H-ML2			
			7.15 Nm	1500 W	R88M-G1K520T-□S2	R88D-GN15H-ML2			
			1000 min <sup>-1</sup>	8.62 Nm	R88M-G90010T-□S2	R88D-GN15H-ML2			
Flat	100-400 W 	3000 min <sup>-1</sup>	0.32 Nm	100 W	R88M-GP10030□-□S2	R88D-GN01H-ML2	R88D-GT01H		
			0.64 Nm	200 W	R88M-GP20030□-□S2	R88D-GN02H-ML2	R88D-GT02H		
			1.3 Nm	400 W	R88M-GP40030□-□S2	R88D-GN04H-ML2	R88D-GT04H		

## Type designation

### Servo drive

### R88D-GN04H-ML2

G-Series servo drive

Drive type

T: Analogue/ pulse type

N: Network type

Capacity

01	100 W
02	200 W
04	400 W
08	750 W
10	1.0 kW
15	1.5 kW

Model

Blank: Analogue/ pulse type

ML2: MECHATROLINK-II communications

Source voltage

H: 230 V

## Servo drive specifications

### General specifications

Servo drive type	R88D-G□	01H□	02H□	04H□	08H□	10H□	15H□								
Applicable servomotor	R88M-G□	05030□/10030□	20030□	40030□	75030□	G1K020T□	90010T□ / 1K030T□ / 1K5□0T□								
	R88M-GP□	10030□	20030□	40030□	-	-	-								
Basic specifications	Max. applicable motor capacity W	100	200	400	750	1000	1500								
	Continuous output current Arms	1.16	1.6	2.7	4.0	5.9	9.8								
	Max. output current Arms	3.5	5.3	7.1	14.1	21.2	28.3								
	Input power	Main circuit	For single-phase, 200 to 240 VAC +10 to -15% (50/60 Hz)		For single-phase/ three-phase, 200 to 240 VAC +10 to -15% (50/60 Hz)										
	Supply	Control circuit	For single-phase, 200 to 240 VAC + 10 to -15% (50/60 Hz)												
	Control method	IGBT-driven PWM method													
	Feedback	Serial encoder (incremental/absolute)													
	Conditions	Usage/storage temperature	0 to +55 °C / -20 to 65 °C												
		Usage/storage humidity	90% RH or less (non-condensing)												
		Altitude	1000m or less above sea level												
		Vibration/shock resistance	5.88 m/s <sup>2</sup> / 19.6 m/s <sup>2</sup>												
		Configuration	Base mounted												
	Approx. weight	Kg	0.8	1.1	1.5	1.7									

## MECHATROLINK-II servo drive specifications

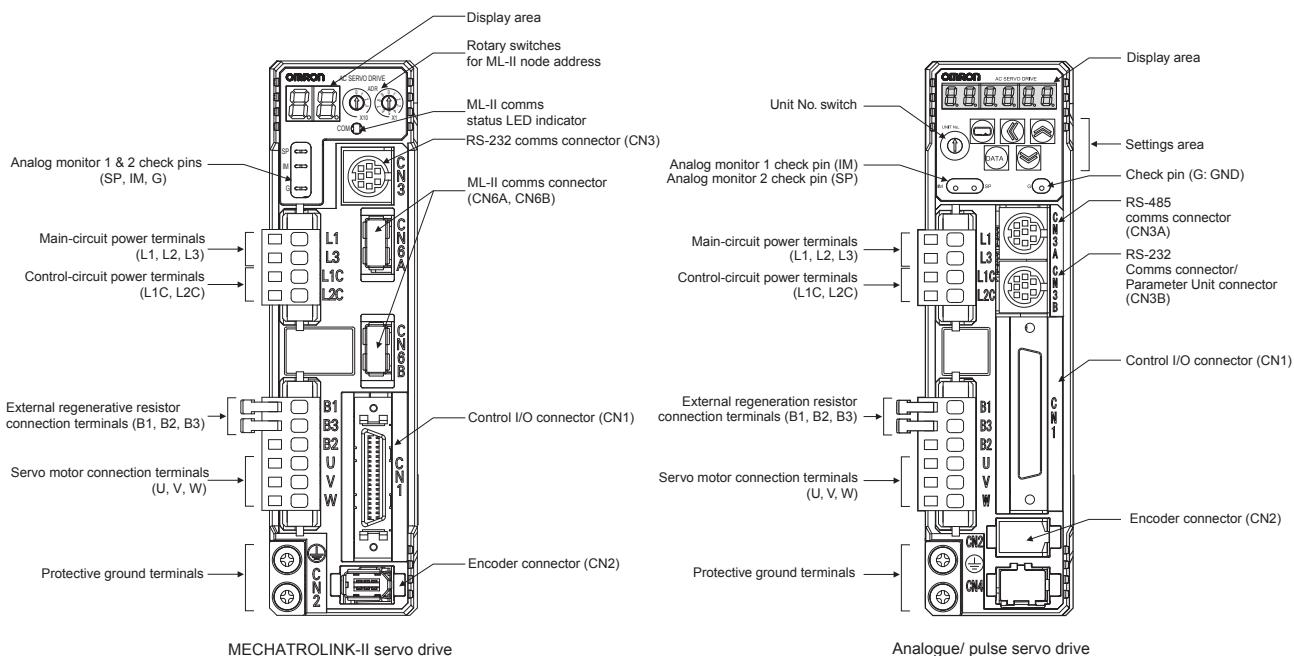
Position/Speed/torque control mode Performance Command Input I/O signal	Speed variance	Load variance	During 0 to 100% load $\pm 0.01$ max. (at rated speed)
	Voltage variance	0% at $\pm 10\%$ of rated voltage (at rated speed)	
	Temperature variance	0 to 50°C $\pm 0.1\%$ max. (at rated speed)	
	Frequency characteristics	1 kHz	
	Torque control accuracy (reproducibility)	$\pm 3\%$ (at 20% to 100% of rated torque)	
	Soft start time setting	0 to 10 s (acceleration time and deceleration time can be set)	
	MECHATROLINK Communication	MECHATROLINK-II commands (for sequence, motion, data setting/reference, monitor, adjustment and other commands)	
	Sequence input signal	Emergency stop, 3 external latch signals, forward/reverse torque limit, forward/reverse run prohibit, origin proximity, 3 general-purpose inputs	
	Sequence output signal	It is possible to output three types of signals: positioning completed, speed coincidence, rotation speed detection, servo ready, current limit, speed limit, brake release and warning signal	
	RS-232 communications	Interface	Personal computer
Integrated functions Communications		Transmission rate	From 2400 to 57600 bps
		Functions	Parameter setting, status display, alarm display (monitor, clear, history), servo drive data tracing function, test run/autotuning operations, real time trace, absolute encoder setting, default values function
	MECHATROLINK communications	Communications protocol	MECHATROLINK-II
		Transmission rate	10 Mbps
		Data length	32 bytes
		Functions	Parameter setting, status display, alarm display (monitor, clear, history), default values function
	Tuning		Horizontal and vertical axis mode. One parameter rigidity setting. Load inertia detection.
	Dynamic brake (DB)		Operates when main power OFF, servo alarm, overtravel or servo OFF
	Regenerative processing		Built-in regeneration resistor in models from 750 W to 1.5 kW. External regeneration resistor optionally.
	Overtravel (OT) prevention function		Dynamic brake, disables torque or emergency stop torque during POT and NOT operation
Integrated functions Protective functions	Emergency stop (STOP)		Emergency stop input
	Encoder divider function		Optional division pulses possible
	Electronic gearing		$0,01 < \text{Numerator/Denominator} < 100$
	Internal speed setting function		8 internal speeds
	Protective functions		Overvoltage, undervoltage, overcurrent, overload, regeneration overload, servo drive overheat
	Analog monitor Output		The actual servomotor speed, command speed, torque and number of accumulated pulses can be measured using an oscilloscope or other device.
	Panel operator	Display functions	A 2-digit 7-segment LED display shows the servo drive status, alarm codes, parameters, etc. MECHATROLINK-II communications status LED indicator (COM)
		Switches	Rotary switch for setting the MECHATROLINK-II node address

## Analog/pulse servo drive specifications

Control mode Performance Position control Speed/torque control	Control mode		Position, speed and torque control mode
	Speed variance	Load variance	During 0 to 100% load $\pm 0.01$ max. (at rated speed)
	Voltage variance	0% at $\pm 10\%$ of rated voltage (at rated speed)	
	Temperature dependence	0 to 50°C $\pm 0.1\%$ max. (at rated speed)	
	Frequency characteristics	1 kHz	
	Torque control accuracy (reproducibility)	$\pm 3\%$ (at 20% to 100% of rated torque)	
	Soft start time setting	0 to 10 s (acceleration time and deceleration time can be set)	
	Input signal	Command pulse	Input pulse type Signal + pulse, 90° phase displacement 2-phase pulse (phase A/B) or reverse and forward pulses (CW/CCW) Input pulse frequency 500 kpps max. line-driver input, 200 kpps max. open-collector input Electronic gearing $0,01 < \text{Numerator/Denominator} < 100$
	Input signal	Speed control	Speed reference voltage 10 VDC at 3000 r/min: set at delivery (the scale can be set by parameters) Torque limit 3 VDC at rated torque (torque can be limited separately in positive/negative direction) Preset speed control Preset speed is selectable from 8 internal settings by digital inputs.
	Input signal	Torque control	Torque reference voltage 3 VDC at rated torque: set at delivery (the scale and polarity can be set by parameters). Speed limit Speed limit can be set by parameter.
I/O signal	Sequence input signal		Forward/reverse run prohibit, deviation counter reset, alarm reset, control mode switch, pulse prohibited, speed selection, gain switch, zero speed designation, origin proximity
I/O signal	Sequence output signal		Brake release, servo ready and alarm output. It is possible also to output two types of configurable signals: current limit, rotation speed detection, warning signal, speed coincidence, positioning completed

<b>Integrated functions</b>	RS-232 communications	Interface	Personal computer
		Transmission rate	From 2400 to 57600 bps
		Functions	Parameter setting, status display, alarm display (monitor, clear, history), servo drive data tracing function, test run/autotuning operations, real time trace, absolute encoder setting, default values function
	RS-485 communications data	Interface	Communication data interface between servo drives and personal computer.
		Transmission rate	From 2400 to 57600 bps
		Functions	Parameter setting, status display, alarm display (monitor, clear, history), servo drive data tracing function, test run/autotuning operations, real time trace, absolute encoder setting, default values function
	Tuning	HORIZONTAL AND VERTICAL AXIS MODE	Horizontal and vertical axis mode. One parameter rigidity setting. Load inertia detection.
	DYNAMIC BRAKE (DB)	OPERATES WHEN MAIN POWER OFF, SERVO ALARM, OVERTRAVEL OR SERVO OFF	
	REGENERATIVE PROCESSING	BUILT-IN REGENERATION RESISTOR IN MODELS FROM 750 W TO 1.5 kW. EXTERNAL REGENERATION RESISTOR OPTIONAL.	
	OVERTRAVEL (OT) PREVENTION FUNCTION	DYNAMIC BRAKE, DISABLES TORQUE OR EMERGENCY STOP TORQUE DURING POT AND NOT OPERATION	
	EMERGENCY STOP (STOP)	EMERGENCY STOP INPUT	
	ENCODER DIVIDER FUNCTION	OPTIONAL DIVISION PULSES POSSIBLE	
	PROTECTIVE FUNCTIONS	OVERTOWTAGE, UNDERTOWTAGE, OVERCURRENT, OVERLOAD, REGENERATION OVERLOAD, SERVO DRIVE OVERHEAT	
	ANALOG MONITOR OUTPUT	THE ACTUAL SERVOMOTOR SPEED, COMMAND SPEED, TORQUE AND NUMBER OF ACCUMULATED PULSES CAN BE MEASURED USING AN OSCILLOSCOPE OR OTHER DEVICE.	
	Panel operator	Display functions	A 6-digit 7-segment LED display shows the servo drive status, alarm codes, parameters, etc.
		Switches	Unit No. switch for serial communications. Value from 0 to F. To identify which servo drive the computer is accessing in RS232 communications when multiple servo drives.

## Servo drive part names



## I/O specifications

### Main circuit connector (CNA) specifications

Symbol	Name	Function
L1	Main circuits power supply input	AC power input terminals for the main circuit <b>Note:</b> for single-phase connect the power supply input to L1 and L3
L2		
L3		
L1C	Control circuit power supply input	AC power input terminals for the control circuit
L2C		

### Servomotor connector (CNB) specifications

Symbol	Name	Function
B1	External regeneration resistor connection terminals	Up to 400 W: If regenerative energy is high, connect an external regeneration resistor between B1 and B2.
B2		From 750 W to 1.5kW: Normally B2 and B3 are connected. If regenerative energy is high, remove the short-circuit bar between B2 and B3 and connect an external regeneration resistor between B1 and B2.
B3		
U	Servo motor connection terminals	Terminals for outputs to the servomotor.
V		
W		
(+)	Frame ground	Ground terminal. Ground to 100Ω or less.
(-)		

### I/O signals (CN1) - Input signals (for MECHATROLINK-II servo drives)

Pin No.	Signal name	Function
1	+24VIN	Control power supply input for sequence signals: users must provide the +24 V power supply. Allowable voltage range: 12 to 24 VDC
2	STOP	Emergency Stop Input Input for emergency stop. Emergency stop function factory default: enable.
3	EXT3	External Latch Signals
4	EXT2	
5	EXT1	Minimal signal width must be 1 ms.
22	IN1	External general-purpose Input 0
6	IN0	External general-purpose Input 1
23	IN2	External general-purpose Input 2
7	PCL	Forward Torque Limit Input
8	NCL	Reverse Torque Limit Input
19	POT	Forward Run Prohibit Input
20	NOT	Reverse Run Prohibit Input
21	DEC	Origin Proximity Input
34	BAT	Battery backup input for absolute encoder
33	BATCOM	Connecting pin for the absolute backup battery. Do not connect when a battery is connected to the servomotor encoder cable.

### I/O signals (CN1) - output signals (for MECHATROLINK-II servo drives)

Pin No.	Signal name	Function
15	/ALM	The output turns OFF when an alarm is generated in the Servo drive.
16	ALMCOM	
29	OUTM2	General-purpose output.
30	OUTM2COM	
31	OUTM3	The function for this output is selected by changing the parameter: INP1 (Positioning completed), VCMP (Speed conformity signal), TGON (Servomotor rotation speed detection), READY (Servo ready), CLIM (Current limit detection), VLIM (Speed limit detection), BKIR (Brake interlock), WARN (Warning signal)
32	OUTM3COM	
36	OUTM1	
35	OUTM1COM	

### I/O signals (CN1) - Input signals (for analog/pulse servo drives)

Pin No.	Control mode	Signal name	Function
1	Position	+24 VCW	Reference pulse input for line driver and open collector according to parameter setting.
3		+CW	
4		-CW	Input mode: Sign + pulse string
2		+24 VCW	Reverse/forward pulse (CCW/CW pulse)
5		+CCW	Two-phase pulse (90° phase differential)
6		-CCW	
44		+CWLD	Reference pulse input for line driver only.
45		-CWLD	
46		+CCWL	Input mode: Reverse/forward pulse (CW/CCW pulse)
47		-CCWL	
14	Speed	REF	Speed reference input: ±10 V/rated motor speed (input gain can be modified using a parameter).
Torque		TREF1	Torque reference input: ±10 V/rated motor torque (input gain can be modified using a parameter).
VLIM			Speed limit input: ±10 V/rated motor speed (input gain can be modified using a parameter).
15	-	AGND1	Analog signal ground
16	Torque	TREF2	Torque reference input: ±10 V/rated motor torque (input gain can be modified using a parameter).
Position/Speed	PCL		Forward torque limit input: ±10 V/rated motor torque (input gain can be modified using a parameter).
		NCL	Reverse torque limit input: ±10 V/rated motor torque (input gain can be modified using a parameter).
17	-	AGND	Analog signal ground

Pin No.	Control mode	Signal name	Function	
7	Common	+24 VIN	Control power supply input for sequence signals: users must provide the +24 V power supply (12 to 24 V).	
29		RUN	Servo ON: this turn ON the servo.	
26	Position	DFSEL	Vibration filter switching	Enables vibration filter according parameter setting.
	Speed	PNSEL	Speed command rotation direction switch	
	Speed/Torque	VZERO	Zero speed designation	Speed command is regarder as 0. This function is enable/disabled by parameter.
27	Common	GSEL	Gain switching	Enables gain value according parameter setting.
		TLSEL	Torque limit switch.	
28	Position	GESEL	Electronic gear switching	Switches the numerator fro electronic gear ratio.
	Speed	VSEL3	Internal speed selection 3	Input to select the desired speed setting during internally speed operation. The speed selecton is combining this input with VSEL1 and VSEL2 inputs.
30	Position	ECRST	Error counter reset input.	Resets the position error counter.
	Speed	VSEL2	Internal speed selection 2	Input to select the desired speed setting during internally speed operation. The speed selecton is combining this input with VSEL1 and VSEL3 inputs.
31	Common	RESET	Alarm reset input.	Release the alarm status. The error counter is reset when the alarm is reset.
32	Position/ Speed/Torque	TVSEL	Control mode switching	Position ↔ speed Position ↔ torque Torque ↔ speed } Enables control mode switching
33	Position	IPG	Pulse prohibition input. Digital input to inhibit the position reference pulse.	
	Speed	VSEL1	Internal speed selection 1	
8	Common	NOT	Reverse run prohibited	Overtravel prohibited: stops servomotor when movable part travels beyond the allowable range of motion.
		POT	Forward run prohibited	
20	Common	SEN	Sensor ON input. Initial data request signal when using an absolute encoder.	
13		SENGND	Sensor ON signal ground.	
42	Common	BAT (+)	Backup battery connection terminals when the absolute encoder power is interrupted. Do not connect when an absolute encoder battery cable for backup is used.	
43		BATGND (-)		
50		FG	Frame ground	

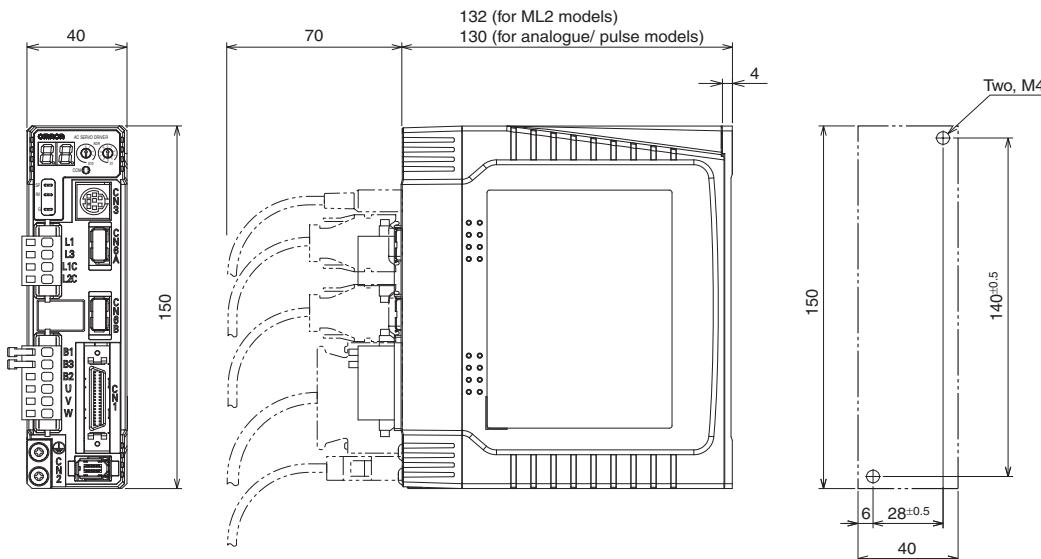
**I/O signals (CN1) - Output signals (for analog/pulse servo drives)**

Pin No.	Control mode	Signal name	Function	
21	Common	+A	Encoder phase A+	Encoder signals are output according Encoder Dividing Numerator parameter. This is the line-driver output (equivalent to R422).
22		-A	Encoder phase A-	
49		+B	Encoder phase B+	
48		-B	Encoder phase B-	
23		+Z	Encoder phase Z+	
24		-Z	Encoder phase Z-	
19		Z	Encoder phase-Z output	
25		ZCOM	Encoder phase-Z common	
11		BKIR	Brake release signal output	
10		BKIRCOM		Timing signal for operating the electromagnetic brake on a motor.
35		READY	Servo ready: ON if there is not servo alarm when the control/main circuit power supply is turned ON.	
34		READYCOM		
37		/ALM	Servo alarm: turns OFF when an error is detected.	
36		ALMCOM		
39	Speed/torque	TGON	Motor rotation speed detection. This output turns ON when the motor rotation speed reaches the speed set in a parameter.	
38		TGONCOM		
39	Position	INP	Positioning complete output: turns ON when position error is equal to setting parameter.	
38		INPCOM		
-	-	INP2	Position complete output 2	The function of output signals allocated to pins 11,10, 34 to 39 can be changed with these options by parameters settings.
		P-CMD	Position command status	
		ZSP	Zero speed	
		WARN1	Warning 1	
		WARN2	Warning 2	
		ALM-ATB	Alarm output	
		VCMP	Speed conformity output	
		V-CMD	speed command status	
		V-LIMIT	Speed limit detection	
		T-LIMIT	Torque limit detection	
12	Common	OUTM1	General-purpose Output 1	Use the parameter settings to assign the desired function
40		OUTM2	General-purpose Output2	
41		COM	General-purpose common	

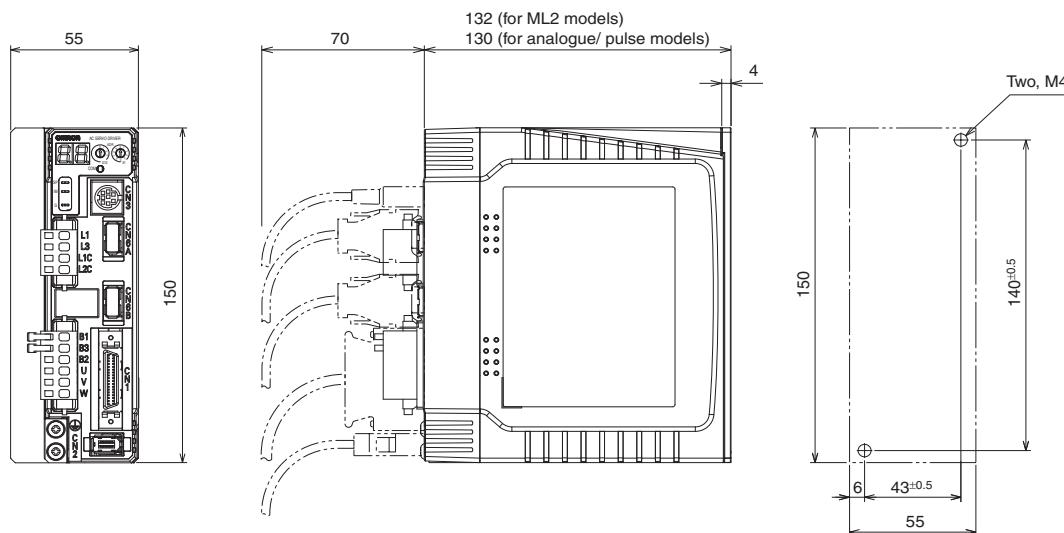
## Dimensions

### Servo drives

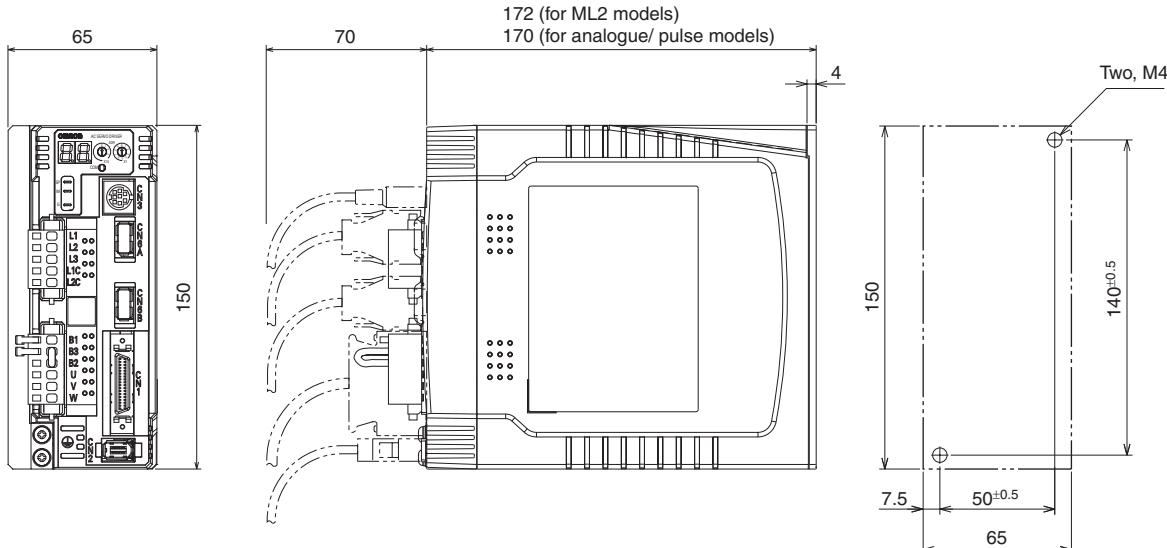
#### R88D-GN01/02H-ML2, R88D-GT01/02H (200 V, 100 to 200 W)



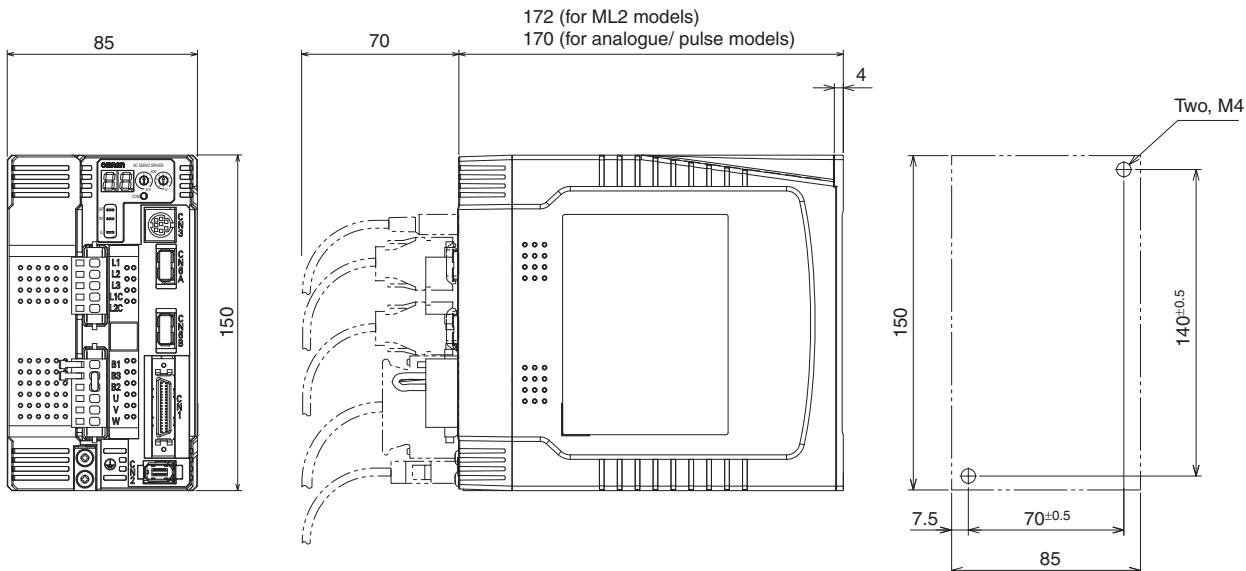
#### R88D-GN04H-ML2, R88D-GT04H (200 V, 400 W)



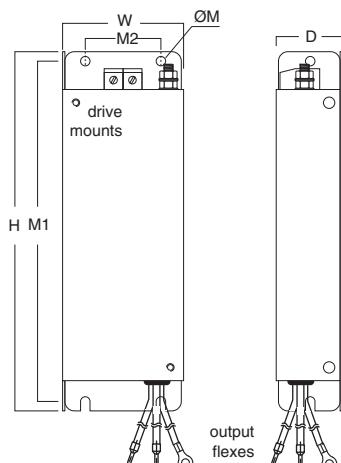
#### R88D-GN08H-ML2, R88D-GT08H (200 V, 750 W)



## R88D-GN10/15H-ML2, R88D-GT10/15H (200 V, 1 kW to 1.5 kW )



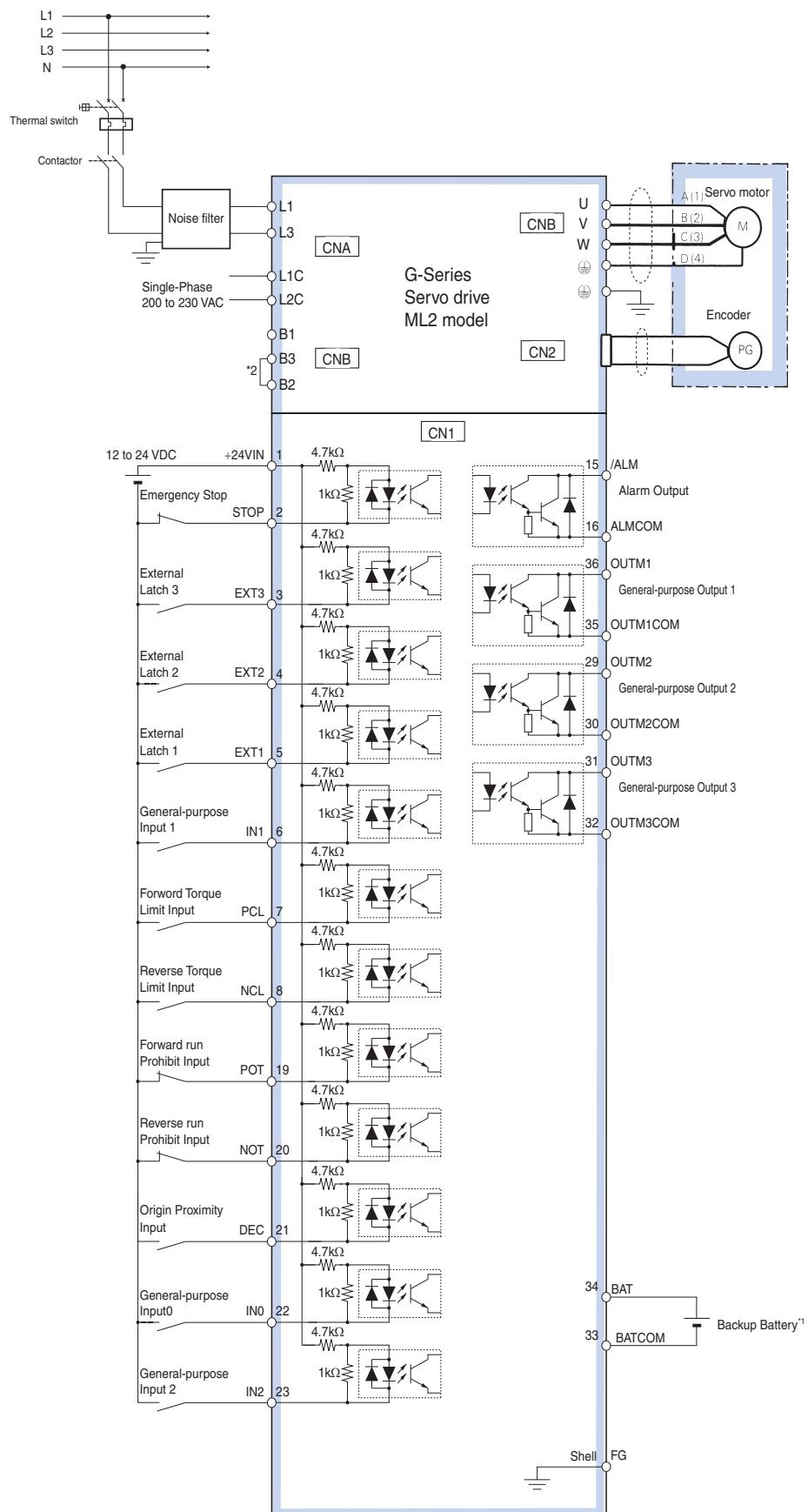
## Filters



Filter model	Rated current	Leakage current	External dimensions			Mount dimensions		Filter Fixing	Rated voltage
			H	W	D	M1	M2		
R88A-FIK102-RE	2.4 A	3.5 mA	190	42	44	180	20	M4	250 VAC single-phase
R88A-FIK104-RE	4.1 A	3.5 mA	190	57	30	180	30	M4	
R88A-FIK107-RE	6.6 A	3.5 mA	190	64	35	180	40	M4	
R88A-FIK114-RE	14.2 A	3.5 mA	190	86	35	180	60	M4	

## Installation

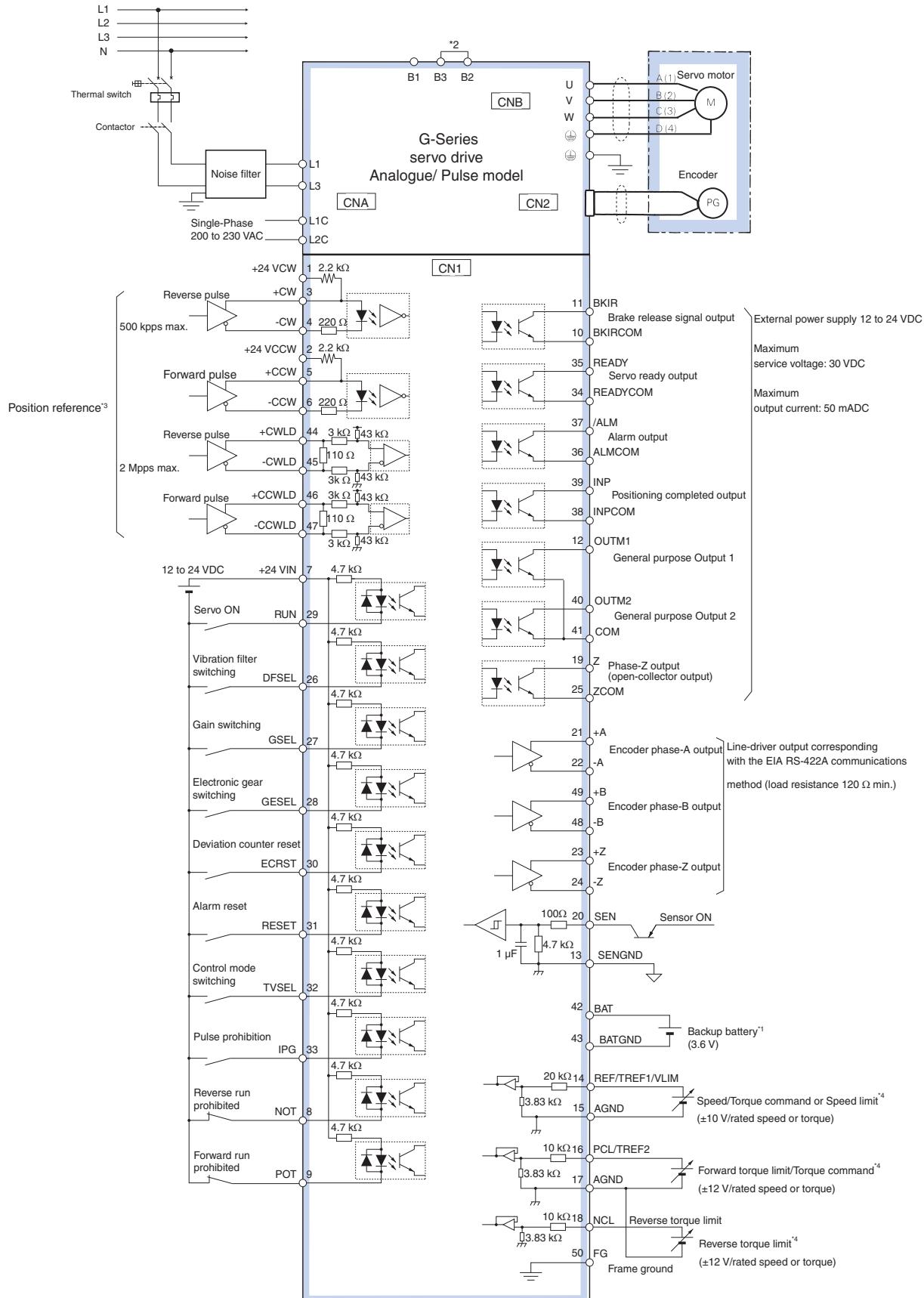
### Single-phase, 230 VAC



\*1 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.

\*2 For servo drives from 750 W, B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external resistor between B1 and B2.

## Single-phase, 230 VAC



\*1 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.

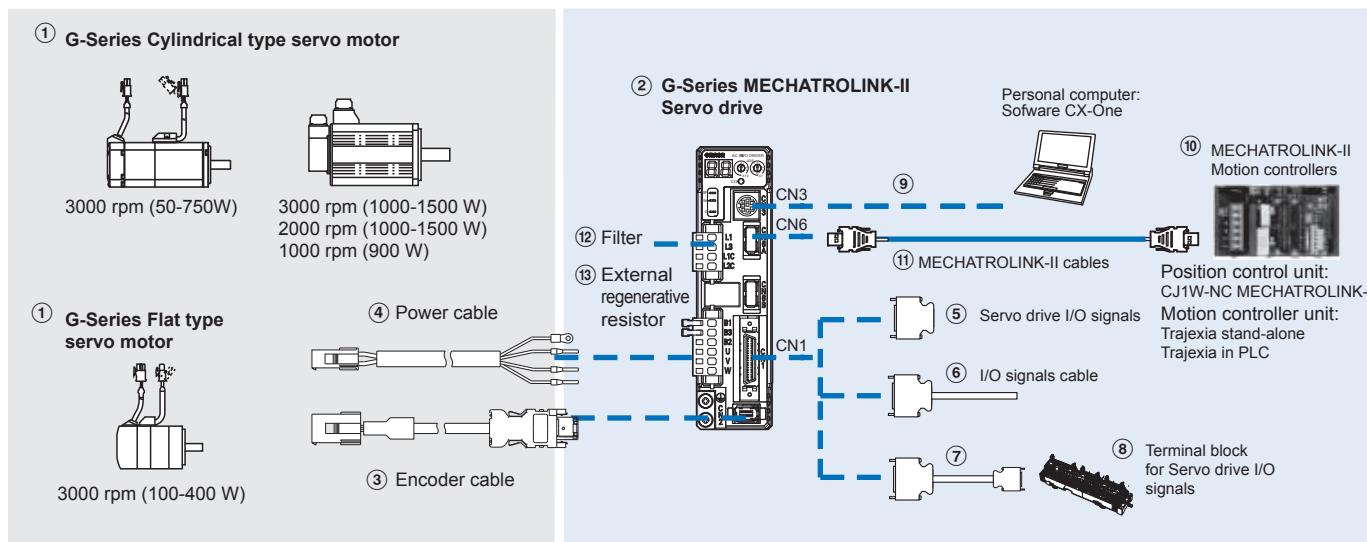
\*2 For servo drives from 750 W, B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external resistor between B1 and B2.

\*3 Only available in Position control mode.

\*4 The input function depends on control mode used (Position, speed or torque control).

## Ordering information

### G-Series MECHATROLINK-II model reference configuration



Note: The symbols ① ② ③ ④ ⑤... show the recommended sequence to select the components in a G-Series servo system

#### Servo motors, power & encoder cables

Note: ①③④ Refer to the G-Series servo motor chapter for servomotor, motor cables or connectors selection

#### Servo drives

	Specifications	Servo drive model	① Compatible rotary servo motors	
② 1 phase 200 VAC	100 W 200 W 400 W 750 W 1.0 kW 1.5 kW	R88D-GN01H-ML2 R88D-GN02H-ML2 R88D-GN04H-ML2 R88D-GN08H-ML2 R88D-GN10H-ML2 R88D-GN15H-ML2	Cylindric type	Flat type
			R88M-G05030□	R88M-GP10030□
			R88M-G10030□	
			R88M-G20030□	R88M-GP20030□
			R88M-G40030□	R88M-GP40030□
			R88M-G75030□	-
			R88M-G1K020T□	-
			R88M-G90010T□	-
			R88M-G1K030T□	-

#### Control cables (for CN1)

Symbol	Name	Connect to	Model
⑤	I/O connector kit	Servo drive I/O signals	R88A-CNU01C
⑥	General purpose cable		R88A-CPGB001S-E R88A-CPGB002S-E
⑦	Terminal block cable		XW2Z-100J-B33 XW2Z-200J-B33
⑧	Terminal block		XW2B-20G4 XW2B-20G5 XW2D-20G6

#### Computer cable (for CN3)

Symbol	Name	Model
⑨	Computer cable RS232	2 m R88A-CCG002P2

#### MECHATROLINK-II Motion controllers

Symbol	Name	Model
⑩	Trajexia stand-alone motion controller	TJ2-MC64 (64 axes) TJ1-MC16 (16 axes) TJ1-MC04 (4 axes)
	Trajexia-PLC motion controller	CJ1W-MCH72 (30 axes) CJ1W-MC472 (4 axes)
	Position Controller Unit for CJ1 PLC	CJ1W-NCF71 (16 axes) CJ1W-NC471 (4 axes) CJ1W-NC271 (2 axes)
	Position Controller Unit for CS1 PLC	CS1W-NCF71 (16 axes) CS1W-NC471 (4 axes) CS1W-NC271 (2 axes)

#### MECHATROLINK-II cables (for CN6)

Symbol	Specifications	Length	Model
⑪	MECHATROLINK-II Terminator resistor	-	JEPMC-W6022-E
	MECHATROLINK-II cables	0.5 m	JEPMC-W6003-A5-E
		1 m	JEPMC-W6003-01-E
		3 m	JEPMC-W6003-03-E
		5 m	JEPMC-W6003-05-E
		10 m	JEPMC-W6003-10-E
		20 m	JEPMC-W6003-20-E
		30 m	JEPMC-W6003-30-E

#### Filters

Symbol	Applicable servodrive	Filter model	Rated current	Leakage current	Rated voltage
⑫	R88D-GN01H□	R88A-FIK102-RE	2.4 A	3.5 mA	250 VAC single-phase
	R88D-GN02H□				
	R88D-GN04H□	R88A-FIK104-RE	4.1 A	3.5 mA	
	R88D-GN08H□	R88A-FIK107-RE	6.6 A	3.5 mA	
	R88D-GN10H□	R88A-FIK114-RE	14.2 A	3.5 mA	
	R88D-GN15H□				

#### External regenerative resistor

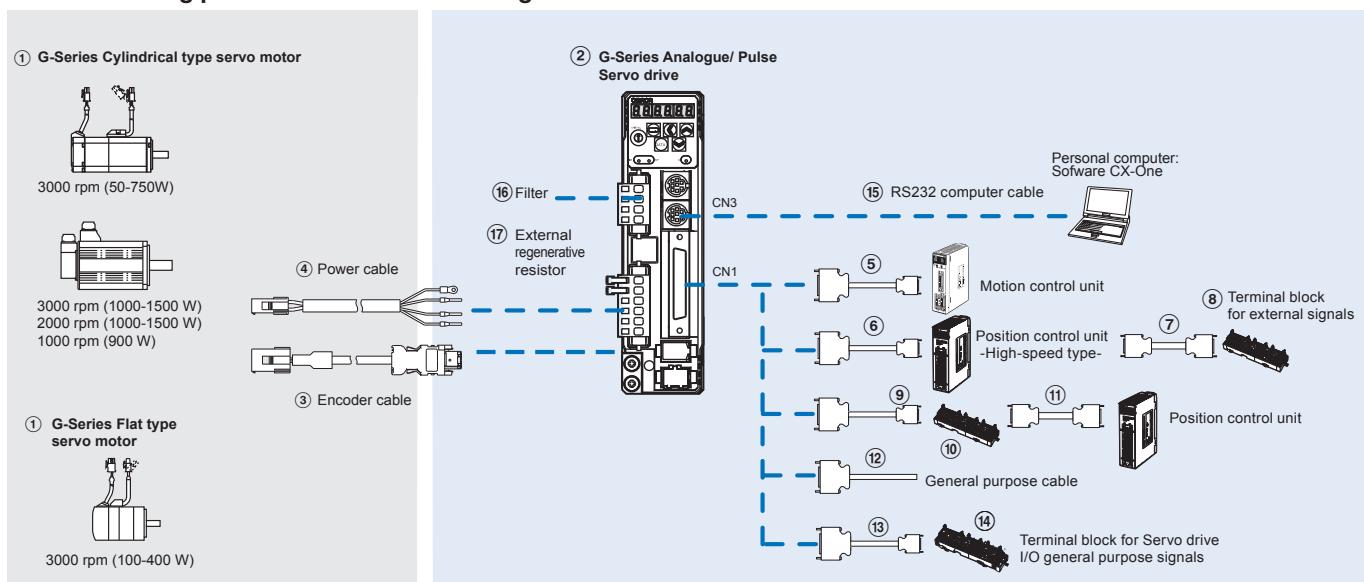
Symbol	Regenerative resistor unit model	Specifications
⑬	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

#### Computer software

Specifications	Model
Configuration and monitoring software tool for servo drives and inverters. (CX-drive version 1.70 or higher)	CX-drive
Complete OMRON software package including CX-drive. (CX-One version 3.10 or higher)	CX-One

## Ordering information

### G-Series Analog/pulse model reference configuration



**Note:** The symbols ①②③④⑤... show the recommended sequence to select the components in a G-Series servo system

### Servo motors, power & encoder cables

**Note:** ①③④ Refer to the G-Series servo motor chapter for servomotor, motor cables or connectors selection

### Servo drives

	Specifications		Servo drive model	(1) Compatible rotary servo motors	
				Cylindric type	Flat type
(2)	1 phase 200 VAC	100 W	R88D-GT01H	R88M-G05030□	R88M-GP10030□
		200 W		R88M-G10030□	
		400 W		R88M-G20030□	R88M-GP20030□
		750 W		R88M-G40030□	R88M-GP40030□
		1.0 kW		R88M-G75030□	-
		1.5 kW		R88M-G1K020T□	-
				R88M-G90010T□	-
				R88M-G1K030T□	-
				R88M-G1K520T□	-
				R88M-G1K530T□	-

### Control cables (for CN1)

Symbol	Description	Connect to		Model
(5)	Control cable (1 axis)	Motion control units CS1W-MC221 CS1W-MC421	1 m	R88A-CPG001M1
			2 m	R88A-CPG002M1
			3 m	R88A-CPG003M1
			5 m	R88A-CPG005M1
	Control cable (2 axis)	Motion control units CS1W-MC221 CS1W-MC421	1 m	R88A-CPG001M2
			2 m	R88A-CPG002M2
			3 m	R88A-CPG003M2
			5 m	R88A-CPG005M2
(6)	Control cable (line-driver output for 1 axis)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434	1 m	XW2Z-100J-G9
			5 m	XW2Z-500J-G9
			10 m	XW2Z-10MJ-G9
	Control cable (open-collector output for 1 axis)	Position control units (high-speed type) CJ1W-NC214 CJ1W-NC414	1 m	XW2Z-100J-G13
			3 m	XW2Z-300J-G13
	Control cable (line-driver output for 2 axis)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434	1 m	XW2Z-100J-G1
			5 m	XW2Z-500J-G1
			10 m	XW2Z-10MJ-G1
	Control cable (open-collector output for 2 axis)	Position control units (high-speed type) CJ1W-NC214 CJ1W-NC414	1 m	XW2Z-100J-G5
			3 m	XW2Z-300J-G5

Symbol	Description	Connect to	Model
(7)	Terminal block cable for external signals (for input common, forward/reverse run prohibited inputs, emergency stop input, origin proximity input and interrupt input)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434 CJ1W-NC214 CJ1W-NC414	0.5 m XW2Z-C50X
(8)	Terminal block for external signals (M3 screw, pin terminals)		1 m XW2Z-100X
	Terminal block for ext. signals (M3.5 screw, fork/round terminals)		2 m XW2Z-200X
	Terminal block for ext. signals (M3 screw, fork/round terminals)		3 m XW2Z-300X
			5 m XW2Z-500X
			10 m XW2Z-010X
			- XW2B-20G4
(9)	Cable from servo relay unit to servo drive	CS1W-NC1□3, CJ1W-NC1□3, C200HW-NC113, CS1W-NC2□3/4□3, CJ1W-NC2□3/4□3, C200HW-NC213/413, CQM1H-PLB21 or CQM1-CPU43 CJ1M-CPU21/22/23	1 m XW2Z-100J-B25
(10)	Servo relay unit		2 m XW2Z-200J-B25
			1 m XW2Z-100J-B31
			2 m XW2Z-200J-B31
(11)	Position control unit connecting cable	CQM1H-PLB21 or CQM1-CPU43 CS1W-NC113 or C200HW-NC113 CS1W-NC213/413 or C200HW-NC213/413 CS1W-NC133 CS1W-NC233/433 CJ1W-NC113 CJ1W-NC213/413 CJ1W-NC133 CJ1W-NC233/433 CJ1M-CPU21/22/23	0.5 m XW2Z-050J-A3
			1 m XW2Z-100J-A3
			0.5 m XW2Z-050J-A6
			1 m XW2Z-100J-A6
			0.5 m XW2Z-050J-A7
			1 m XW2Z-100J-A7
			0.5 m XW2Z-050J-A10
			1 m XW2Z-100J-A10
			0.5 m XW2Z-050J-A11
			1 m XW2Z-100J-A11
			0.5 m XW2Z-050J-A14
			1 m XW2Z-100J-A14
(12)	General purpose cable	For general purpose controllers	0.5 m XW2Z-050J-A15
(13)	Terminal block cable		1 m XW2Z-100J-A15
(14)	Terminal block (M3 screw and for pin terminals)	For general purpose controllers	1 m XW2Z-100J-A18
	Terminal block (M3.5 screw and for fork/round terminals)		0.5 m XW2Z-050J-A19
	Terminal block (M3 screw and for fork/round terminals)		1 m XW2Z-100J-A19
			0.5 m XW2Z-050J-A33
			1 m XW2Z-100J-A33

**Computer cable (for CN3)**

Symbol	Name	Model
(15)	Computer cable RS232	2 m R88A-CCG002P2

**Connectors**

Specifications	Model
I/O connector kit, 50 pins (for CN1)	R88A-CNU11C

**Filters**

Symbol	Applicable servodrive	Filter model	Rated current	Leakage current	Rated voltage
(16)	R88D-GT01H R88D-GT02H	R88A-FIK102-RE	2.4 A	3.5 mA	250 VAC single-phase
	R88D-GT04H	R88A-FIK104-RE	4.1 A	3.5 mA	
	R88D-GT08H	R88A-FIK107-RE	6.6 A	3.5 mA	
	R88D-GT10H R88D-GT15H	R88A-FIK114-RE	14.2 A	3.5 mA	

**Computer software**

Specifications	Model
Configuration and monitoring software tool for servo drives and inverters. (CX-drive version 1.70 or higher)	CX-drive
Complete OMRON software package including CX-drive. (CX-One version 3.10 or higher)	CX-One

**External regenerative resistor**

Symbol	Regenerative resistor unit model	Specifications
(17)	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.  
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.